Milestones:

* Up to the progress of the group
* Dates do no change

Objectives:

* Only 1 remnant
* Whole map need to be surveyed in order to complete
* Must return to the initial location (starting)
* Boundary measurements, we do not know, only that it is rectangular.
* Tape colours etc, we do not know yet

GUI:

* Arrow keys on screen is up to us
* Autonomous and manual mode needed and needs to be clear of what the current state is
* She likes the small map idea of fixed robot on map yes
* Colour representations in the map must be changeable (did I hear this right?)
* User entering NGZ must be like a shape not a small line

Others:

* Robot must not touch the detected lines
* Whole details of the area needs to be on the map including our robot
* Routing up to us